

INSTRUCTION MANUAL

MASSIO CONTROLPADS AND KEYPADS

MCP-106, MCP-108, MKP-106, MKP-108



IMPORTANT SAFETY INSTRUCTIONS

- 1. READ these instructions.
- 2. KEEP these instructions.
- 3. HEED all warnings.
- 4. FOLLOW all instructions.
- 5. DO NOT use this apparatus near water.
- 6. CLEAN ONLY with dry cloth.
- 7. DO NOT block any ventilation openings. Install in accordance with the manufacturer's instructions.
- 8. DO NOT install near any heat sources such as radiators, heat registers, stoves, or other apparatus (including amplifiers) that produce heat.
- 9. DO NOT defeat the safety purpose of the polarized or grounding type plug. A polarized plug has two blades with one wider than the other. A grounding type plug has two blades and a third grounding prong. The wider blade or the third prong are provided for your safety. If the provided plug does not fit into your outlet, consult an electrician for replacement of the obsolete outlet.
- 10. PROTECT the power cord from being walked on or pinched, particularly at plugs, convenience receptacles, and the point where they exit from the apparatus.
- 11. ONLY USE attachments/accessories specified by the manufacturer.



- 12. USE ONLY with a cart, stand, tripod, bracket, or table specified by the manufacturer, or sold with the apparatus. When a cart is used, use caution when moving the cart/apparatus combination to avoid injury from tip-over.
- 13. UNPLUG this apparatus during lightning storms or when unused for long periods of time.
- 14. REFER all servicing to qualified service personnel. Servicing is required when the apparatus has been damaged in any way, such as power-supply cord or plug is damaged, liquid has been spilled or objects have fallen into the apparatus, the apparatus has been exposed to rain or moisture, does not operate normally, or has been dropped.
- 15. DO NOT expose this apparatus to dripping or splashing and ensure that no objects filled with liquids, such as vases, are placed on the apparatus.
- 16. To completely disconnect this apparatus from the AC Mains, disconnect the power supply cord plug from the AC receptacle.
- 17. Where the mains plug or an appliance coupler is used as the disconnect device, the disconnect device shall remain readily operable.
- 18. DO NOT overload wall outlets or extension cords beyond their rated capacity as this can cause electric shock or fire.



The exclamation point, within an equilateral triangle, is intended to alert the user to the presence of important operating and maintenance (servicing) instructions in the literature accompanying the product.



The lightning flash with arrowhead symbol within an equilateral triangle is intended to alert the user to the presence of uninsulated "dangerous voltage" within the product's enclosure that may be of sufficient magnitude to constitute a risk of electrical shock to persons.



ESD Warning: The icon to the left indicates text regarding potential danger associated with the discharge of static electricity from an outside source (such as human hands) into an integrated circuit, often resulting in damage to the circuit.

WARNING:

To reduce the risk of fire or electrical shock, do not expose this apparatus to rain or moisture.

WARNING:

No naked flame sources - such as candles - should be placed on the product.

WARNING:

Equipment shall be connected to a MAINS socket outlet with a protective earthing connection.

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ESD WARNING



To avoid ESD (Electrostatic Discharge) damage to sensitive components, make sure you are properly grounded before touching any internal materials.

When working with any equipment manufactured with electronic devices, proper ESD grounding procedures must be followed to make sure people, products, and tools are as free of static charges as possible. Grounding straps, conductive smocks, and conductive work mats are specifically designed for this purpose. These items should not be manufactured locally, since they are generally composed of highly resistive conductive materials to safely drain static discharges, without increasing an electrocution risk in the event of an accident.

Anyone performing field maintenance on AMX equipment should use an appropriate ESD field service kit complete with at least a dissipative work mat with a ground cord and a UL listed adjustable wrist strap with another ground cord



WARNING: Do Not Open! Risk of Electrical Shock. Voltages in this equipment are hazardous to life. No user-serviceable parts inside. Refer all servicing to qualified service personnel.

Place the equipment near a main power supply outlet and make sure that you can easily access the power breaker switch.

WARNING: This product is intended to be operated ONLY from the voltages listed on the back panel or the recommended, or included, power supply of the product. Operation from other voltages other than those indicated may cause irreversible damage to the product and void the products warranty. The use of AC Plug Adapters is cautioned because it can allow the product to be plugged into voltages in which the product was not designed to operate. If the product is equipped with a detachable power cord, use only the type provided with your product or by your local distributor and/or retailer. If you are unsure of the correct operational voltage, please contact your local distributor and/or retailer.

FCC AND CANADA EMC COMPLIANCE INFORMATION:

This device complies with part 15 of the FCC Rules. Operation is subject to the following two conditions:

(1) This device may not cause harmful interference, and (2) this device must accept any interference received, including interference that may cause undesired operation.

NOTE: This equipment has been tested and found to comply with the limits for a Class B digital device, pursuant to part 15 of the FCC Rules. These limits are designed to provide reasonable protection against harmful interference in a residential installation. This equipment generates, uses and can radiate radio frequency energy and, if not installed and used in accordance with the instructions, may cause harmful interference to radio communications. However, there is no guarantee that interference will not occur in a particular installation. If this equipment does cause harmful interference to radio or television reception, which can be determined by turning the equipment off and on, the user is encouraged to try to correct the interference by one or more of the following measures:

- •Reorient or relocate the receiving antenna.
- •Increase the separation between the equipment and receiver.
- •Connect the equipment into an outlet on a circuit different from that to which the receiver is connected.
- •Consult the dealer or an experienced radio/TV technician for help.

Approved under the verification provision of FCC Part 15 as a Class B Digital Device.

Caution: Changes or modifications not expressly approved by the manufacturer could void the user's authority to operate this device.

CAN ICES-3 (B)/NMB-3(B)

EU COMPLIANCE INFORMATION:

Eligible to bear the CE mark; Conforms to European Union Low Voltage Directive 2006/95/EC; European Union EMC Directive 2004/108/EC; European Union Restriction of Hazardous Substances Recast (RoHS2) Directive 2011/65/EU; European Union WEEE (recast) Directive 2012/19/EU.

You may obtain a free copy of the Declaration of Conformity by visiting http://www.amx.com/techcenter/certifications.asp.

WEEE NOTICE:



This appliance is labeled in accordance with European Directive 2012/19/EU concerning waste of electrical and electronic equipment (WEEE). This label indicates that this product should not be disposed of with household waste. It should be deposited at an appropriate facility to enable recovery and recycling.

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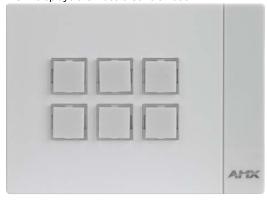
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Overview - Massio ControlPads

The Massio MCP-106 (**FG2102-06**) and MCP-108 (**FG2102-08**) ControlPads each feature built-in Ethernet ports and combine a controller with a 6- or 8-button keypad. The 6-Button Massio ControlPad mounts into a standard 1 gang US, UK, or EU back box. The 8-Button Massio ControlPad mounts into a standard 2 gang US, UK, or EU back box.

FIG. 1 displays the Massio ControlPads.





MCP-106 (Landscape)

MCP-108

FIG. 1 Massio ControlPads

Features

- All-in-one Keypad/Controller Combines a user interface with an on-board controller
- Includes AMX Control Controls all the same devices as NetLinx Integrated Controllers, with the same capabilities and macro functions
- Simple to Program with RPM Uses AMX's Rapid Project Maker (RPM) software to quickly configure and program a system
- Simple Integration with RMS Using RPM, easily integrate AMX's Resource Management Suite (RMS) with a Massio ControlPad to provide a platform for real-time performance monitoring and maintenance
- Display Monitoring Use the ControlPad with RMS to monitor power status, input status, lamp hours and filter hours
- Web-based Control Remotely login to ControlPads and execute button presses
- Inactivity Timer Turn off equipment after lack of activity (timeouts) to save energy
- Built In Control Ports Serial and IR ports available to communicate and control common presentation equipment
- Backlit Buttons Can flash or turn on/off when pressed
- Execute Multiple Functions at Once Macros can be written to trigger multiple functions through a single button press
- Works with AMX IR Files Leverage thousands of pre-existing AMX IR files on AMX.com
- Standard Enclosures Standard back box mounting options for US, UK and EU
- Native Direct Connection to RMS No proxy required
- Master-to-Master Communication The ControlPads support AMX Master-to-Master communication when paired with another AMX Master

Port Assignments by Massio ControlPad

The following table lists the port assignments for Massio ControlPads:

Port Assignments By ControlPad					
ControlPad	RS-232	IR/Serial	Relays	I/O	NetLinx
MCP-106	Port 1	Port 11	N/A	N/A	Port 28
MCP-108	Ports 1-2	Ports 11-12	Port 21	Port 22	Port 28

NOTE: Massio ControlPads do not directly accept NetLinx code. You can configure Massio ControlPads with Rapid Project Maker (RPM). You can only send NetLinx commands to a Massio ControlPad through a Terminal (Telnet) window.

Specifications

The following sections list the specifications for the Massio Control Pads.

MCP-106

The following table lists the specifications for the MCP-106:

MCP-106 Specification	ons		
General:			
Dimensions (HWD):	Portrait: 4 11/16" x 3 7/16" x 9/16" (119 mm x 87.5 mm x 13.9 mm) Landscape: 3 7/16" x 4 11/16" x 9/16" (87.5 mm x 119 mm x 13.9 mm) Mount onto standard 1 gang US, UK, or EU back boxes		
Weight:	Approximately 0.25 lb (0.11 kg)		
Front Panel Components:	6 buttons		
Colors/Styles Available:	 Portrait, Black: MCP-106P-BL (FG2102-06P-B) Portrait, White: MCP-106P-WH (FG2102-06P-W) Landscape, Black: MCP-106L-BL (FG2102-06L-B) Landscape, White: MCP-106L-WH (FG2102-06L-W) 		
Active Power Requirement	nts:		
Voltage, DC (Typical):	PoE (37V-57V)		
Voltage DC Range:	37V-57V per 802.3af specification		
Power Connector:	(1) RJ-45 Ethernet		
Maximum Power Draw:	4.5W		
Power Supply:			
External, Required:	Any POE injector or switch, conforming to the 802.3af standard including AMX's PS-POE-AF-TC (FG423-83), not included		
Environmental:			
Temperature (Operating):	32° F to 104° F (0° C to 40° C)		
Temperature (Storage):	14° F to 140° F (-10° C to 60° C)		
Humidity (Operating):	5% to 85% RH		
Ethernet:			
Ethernet Connection:	(1) 10/100; Port provides TCP/IP communication. This is an Auto MDI/MDI-X enabled port, which allows you to use either straight-through or crossover Ethernet cables. The Ethernet Port LEDs show communication activity, connection status, speeds, and mode information.		
Control Ports and Indicat	Control Ports and Indicators:		
RS-232 Port:	(1) 3-position 3.5mm Screw Terminal; 300 - 115,200 baud		
IR/Serial Port:	(1) 2-position 3.5mm Screw Terminal; IR Transmit / 1-way Serial ports Support high-frequency carriers up to 1.142 MHz		
Program Port:	(1) USB Mini-B, USB		
ID Pushbutton	Reset factory settings, reset factory image, toggle between DHCP or static IP addressing mode		
Memory:			
Flash:	4 GB		
Memory Card:	4 GB SD		
DDRAM:	256 MB		
Certifications:	• FCC Class B • CE EN 55022 • EN 55024 • IEC/EN-60950-1 • UL 60950-1		

MCP-108

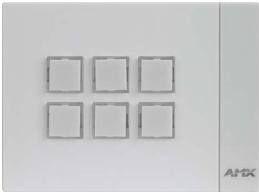
The following table lists the specifications for the MCP-108:

MCP-108 Specification	ns		
General:			
Dimensions (HWD):	4 11/16" x 6" x 1" (119 mm x 152.5 mm x 26 mm)		
Weight:	Approximately 0.41 lb (0.19 kg)		
Mounting Options:	Mount onto standard 2 gang US, UK, or EU back boxes		
Front Panel Components:			
From Paner Components.	8 Buttons 1 Volume Knob with Push Mute		
	7 LED Bar Graph Indicator		
Colors Available:	• Black: MCP-108-BL (FG2102-08-B)		
	• White: MCP-108-WH (FG2102-08-W)		
Active Power Requiremen	its:		
Voltage, DC (Typical):	PoE (37V-57V)		
Voltage DC Range:	37V-57V per 802.3af specification		
Power Connector:	(1) RJ-45 Ethernet		
Maximum Power Draw:	5.0W, plus any power used by the I/O port, which can draw up to an additional 6.0W.		
Power Supply:			
External, Required:	Any POE injector or switch, conforming to the 802.3af standard including AMX's PS-POE-AF-TC (FG423-83), not included		
Environmental:			
Temperature (Operating):	32° F to 104° F (0° C to 40° C)		
Temperature (Storage):	14° F to 140° F (-10° C to 60° C)		
Humidity (Operating):	5% to 85% RH		
Ethernet:			
Ethernet Connection:	(1) 10/100; Port provides TCP/IP communication. This is an Auto MDI/MDI-X enabled port, which allows you to use either straight-through or crossover Ethernet cables. The Ethernet Port LEDs show communication activity, connection status, speeds, and mode information.		
Control Ports and Indicate	ors:		
RS-232 Port:	(2) 3-position 3.5mm Screw Terminals; 300 - 115,200 baud		
IR/Serial Port:	(2) 2-position 3.5mm Screw Terminals; IR Transmit / 1-way Serial ports Support high-frequency carriers up to 1.142 MHz		
I/O Channels:	(1) 4-position 3.5 mm Screw Terminal; 2-channel binary I/O port for contact closure with each input being capable of voltage sensing		
Relay Connection:	(1) 4-position 3.5mm Screw Terminal; (2) single-pole, single-throw relays		
	Each relay can switch up to 24 V _{DC} or 28 V _{AC} @ 1 A		
	Each relay is independently controlled		
Program Port:	(1) USB Mini-B, USB		
ID Pushbutton	Reset factory settings, reset factory image, toggle between DHCP or static IP addressing mode		
Memory:			
Flash:	4 GB		
Memory Card:	4 GB SD		
DDRAM:	256 MB		
Certifications:	 FCC Class B CE EN 55022 EN 55024 IEC/EN-60950-1 UL 60950-1 		

Overview - Massio Keypads

The Massio MKP-106 (**FG5793-06**) and MKP-108 (**FG5793-08**) Keypads are keypad-only versions of the Massio ControlPad. The keypads can serve as second user interfaces or as primary UI in spaces that already contain a separate controller. Massio Keypads connect to a controller via Ethernet. The 6-Button Massio Keypad mounts into a standard 1 gang US, UK, or EU back box. The 8-Button Massio Keypad mounts into a standard 2 gang US, UK, or EU back box.

FIG. 2 displays the Massio ControlPads.





MKP-106 (Landscape)

MKP-108

FIG. 2 Massio Keypads

Specifications

The following sections list the specifications for the Massio Keypads.

MKP-106

The following table lists the specifications for the MKP-106:

MKP-106 Specification			
General:			
Dimensions (HWD):	Portrait: 4 11/16" x 3 7/16" x 9/16" (1	,	
	Landscape: 3 7/16" x 4 11/16" x 9/16"	,	
	Mount onto standard 1 gang US, UK, or	EU back boxes	
Weight:	Approximately 0.25 lb (0.11 kg)		
Front Panel Components:	6 buttons		
ID Pushbutton	Reset factory settings, reset factory image	ge, toggle between DHCP or static IP addressing mode	
Colors/Styles Available:	 Portrait, Black: MKP-106P-BL (FG5793-06P-B) Portrait, White: MKP-106P-WH (FG5793-06P-W) Landscape, Black: MKP-106L-BL (FG5793-06L-B) Landscape, White: MKP-106L-WH (FG5793-06L-W) 		
Active Power Requiremen	nts:		
Voltage, DC (Typical):	PoE (37V-57V)		
Voltage DC Range:	37V-57V per 802.3af specification		
Power Connector:	(1) RJ-45 Ethernet		
Regulatory Compliance:	 FCC CFR Title 47 Part 15 CE EN 55022 CE EN 55024 CE EN 60950-1 IEC-60950-1 UL 60950-1 WEEE 		
Power Supply:	1	'	
External, Required:	Any POE injector or switch, conforming to not included.	to the 802.3af standard including AMX's PS-POE-AF-TC (FG423-83),	

MKP-106 Specifications (Cont.)			
Environmental:	Environmental:		
Temperature (Operating):	32° F to 122° F (0° C to 50° C)		
Temperature (Storage):	14° F to 140° F (-10° C to 60° C)		
Humidity (Operating):	5% to 85% RH		
Ethernet:	Ethernet:		
Ethernet Connection:	(1) 10/100; Port provides TCP/IP communication. This is an Auto MDI/MDI-X enabled port, which allows you to use either straight-through or crossover Ethernet cables. The Ethernet Port LEDs show communication activity, connection status, speeds, and mode information.		
Memory:			
Flash:	4 GB		
Memory Card:	4 GB SD		
DDRAM:	256 MB		

MKP-108

The following table lists the specifications for the MKP-108:

MKP-108 Specification	ons		
General:			
Dimensions (HWD):	4 11/16" x 6" x 1" (119 mm x 152.5 mm x 26 mm)		
Weight:	Approximately 0.41 lb (0.19 kg)		
Mounting Options:	Mount onto standard 2 gang US, UK, or EU back boxe	es	
Front Panel Components:	 8 Buttons 1 Volume Knob with Push Mute 7 LED Bar Graph Indicator 		
ID Pushbutton	Reset factory settings, reset factory image, toggle bet	tween DHCP or static IP addressing mode	
Colors Available:	 Black: MKP-108-BL (FG5793-08-B) White: MKP-108-WH (FG5793-08-W) 		
Active Power Requiremen	its:		
Voltage, DC (Typical):	PoE (37V-57V)		
Voltage DC Range:	37V-57V per 802.3af specification		
Power Connector:	(1) RJ-45 Ethernet		
Regulatory Compliance:	 FCC CFR Title 47 Part 15 CE EN 55022 CE EN 55024 CE EN 60950-1 IEC-60950-1 UL 60950-1 	C-Tick CISPR 22 IC CISPR 22 VCCI CISPR 22 ROHS WEEE	
Power Supply:			
External, Required: Any POE injector or switch, conforming to the 802.3af standard including AMX's PS-POE-AF-TC (FG423-83), not included			
Environmental:			
Temperature (Operating):	32° F to 122° F (0° C to 50° C)		
Temperature (Storage):	14° F to 140° F (-10° C to 60° C)		
Humidity (Operating):	5% to 85% RH		
Ethernet:			
Ethernet Connection:	(1) 10/100; Port provides TCP/IP communication. This is an Auto MDI/MDI-X enabled port, which allows you to use either straight-through or crossover Ethernet cables. The Ethernet Port LEDs show communication activity, connection status, speeds, and mode information.		
Memory:			
Flash: 4 GB			
Memory Card:	4 GB SD		
DDRAM:	: 256 MB		

Wiring and Device Connections

Overview

This section describes the device connectors and ports available on each type of Massio ControlPad. Here you can find wiring and electrical capacities for each type of connector.

FIG. 3 displays the rear panel of the MCP-106.

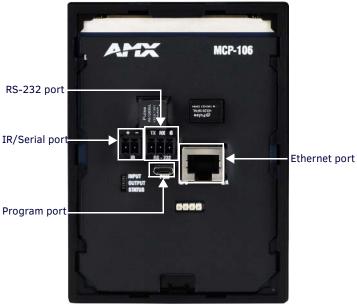


FIG. 3 MCP-106 rear panel

FIG. 4 displays the rear panel of the MCP-108.

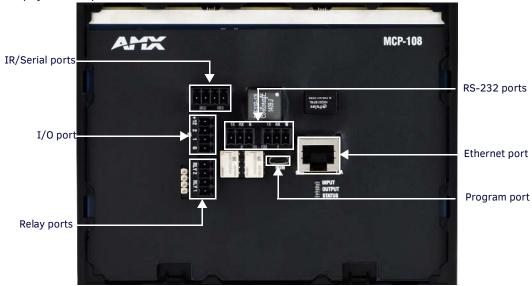


FIG. 4 MCP-108 rear panel

Control Ports and Indicators

The following sub-sections describe each control port on the Massio ControlPads. Refer to *Overview* section on page 12 for the component layout of the rear panels of each type of Massio ControlPad.

RS-232

The Massio ControlPads features up to two RS-232 300-115,200 baud connector ports so you can connect up to two serial devices to the ControlPad. The MCP-106 features one RS-232 connector; the MCP-108 features two connectors. The serial connectors comply with EIA-232-F signal levels. The RX line supports polling for RS-232 devices for statuses such as power status, input status, and lamp hours, so that this information can be provided to RMS.

NOTE: Massio ControlPads do not support RS-422 or RS-485 communications to devices.

FIG. 5 displays the RS-232 ports on the MCP-108.



FIG. 5 RS-232 Serial Ports (MCP-108)

FIG. 6 displays the wiring for the RS-232 connector.

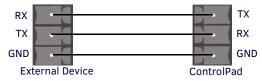


FIG. 6 RS-232 connector wiring

RELAYS

You can connect up to two independent external relay devices to the Relay connectors on the ControlPad. The relay port is only available on the MCP-108.

FIG. 7 displays the RELAYS connector.



FIG. 7 RELAYS connector

Each relay is isolated and normally open.

24 V_{DC} @ 1 A maximum

28 V_{AC} @ 1 A maximum

I/O

The I/O port (available only on the MCP-108) responds to switch closures and voltage level (high/low) changes, or can be used for logic-level outputs. The +12 pin provides +12 V_{DC} @ 200 mA and is designed as a power output for the PCS Power Current Sensors, VSS2 Video Sync Sensors (or equivalent). The GND connector is a common ground and is shared by all I/O ports. A common ground is shared with I/O ports 1 - 2.

FIG. 8 displays the I/O connector.



FIG. 8 I/O port

CAUTION: Improper wiring could damage your ControlPad. The CP-3008 ControlPad has the ground and power signals in swapped positions on the I/O port. If you are replacing a CP-3008 ControlPad with the MCP-108, you may need to make a wiring change in your I/O connector to avoid damaging the MCP-108.

- A contact closure between the GND and an I/O port is detected as a Push.
- When used for voltage inputs, the I/O port detects a low signal (0 1.5 V_{DC}) as a Push, and a high signal (3.5 5 V_{DC}) as a Release. (This I/O port uses 5V logic but can handle up to 12V without harm.)

The following table provides wiring requirements for the I/O port:

I/O Port Wiring Specifications		
Signal	Function	
GND:	Signal GND	
1:	Output	
2:	Output	
+12 V:	PWR	

IR/Serial

You can connect up to two IR-controllable devices to the IR connectors to the Massio ControlPads. The MCP-106 features only one IR connector; the MCP-108 features two connectors.

The IR connectors support generating carriers up to 1.142 MHz. The IR connectors accept an IR Emitter (CC-NIRC) that mounts onto the device's IR window, or a mini-plug (CC-NSER) that connects to the device's control jack.

You can also connect a data (0 - 5 VDC) device.

FIG. 9 displays the IR/SERIAL connector.



FIG. 9 IR/SERIAL connector

The IR/Serial connector wiring specifications are listed in the following table.

IR Connector Wiring Specifications (per Port)			
IR connections	Signal	Function	
1	GND (-) Signal 1 (+)	Signal GND IR data	
2 (MCP-108 only)	GND (-) Signal 2 (+)	Signal GND IR data	

CAUTION: Do NOT connect a power connector to either IR port. Doing so may damage the ControlPad.

LAN (RJ-45)

The LAN RJ-45 port provides 10/100 Mbps communication via Cat5/5e/6 network cable. The LAN port automatically negotiates the connection speed (10 Mbps or 100 Mbps), and whether to use half duplex or full duplex mode. The LAN port is best used for connecting to a network switch. This is an Auto MDI/MDI-X enabled port, which allows you to use either straight-through or crossover Ethernet cables. The port LEDs show communication activity, connection status, speeds, and mode information.

The LAN port also receives its power via the LAN port and Power-over-Ethernet (PoE) when you connect this port to a PoE switch which conforms to the 802.3af standard. See the *Applying Power* section on page 15 for information on PoE setup.

FIG. 10 displays the LAN port.

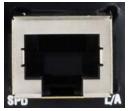


FIG. 10 LAN port

FIG. 11 provides the pinouts and signals for the LAN connector and cable.

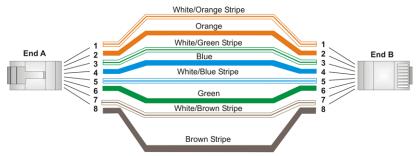


FIG. 11 RJ-45 wiring diagram

NOTE: If Ethernet connectivity is lost on any ControlPad, and then re-established, connectivity may take some time to resume. You will be unable to program the ControlPad until it is fully online.

Applying Power

Applying power to Massio ControlPads and Keypads requires Cat5 cable and a PoE injector, such as the PS-POE-AF-TC (**FG423-83**) available from AMX, or a PoE-capable Ethernet switch which conforms to the 802.3af standard. The network must be connected through the PoE injector to send power to the ControlPad.

- 1. Connect the PoE injector to an AC outlet (~100-240V) using a standard power cord.
- 2. Connect the switch category cable to the Data In port on the PoE injector (FIG. 12).

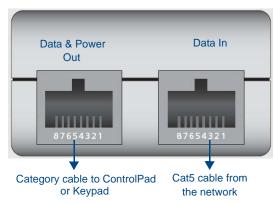


FIG. 12 Connecting to a PoE Injector

Using a separate category cable, connect the Data & Power Out port on the PoE injector to LAN Port on the ControlPad or keypad.

ID Pushbutton

Each Massio ControlPad and Keypad features a pinhole reset pushbutton located on the bottom of the device.

FIG. 13 displays the location of the reset pushbutton on each ControlPad or keypad.

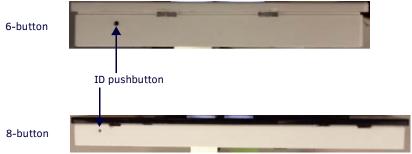


FIG. 13 Location of the ID Pushbuttons on each ControlPad

You can use the ID pushbutton to perform the following procedures:

Perform a factory reset of the ControlPad or Keypad: Press the ID pushbutton for approximately 10 seconds during the
boot process. While pressing the ID pushbutton, disconnect and reconnect the cable from the LAN port on the rear panel
of the ControlPad to reset the ControlPad's factory defaults. During factory reset, the backlight turns off for all buttons,
but all buttons should be back online after 1-2 minutes. If you do not hold in the ID pushbutton for the full 10 seconds,
the reset does not occur. (There is no soft reboot with the ID pushbutton, but you can perform a soft reboot from the
web pages.)

On Massio ControlPads and Keypads, the LEDs on buttons 1 and 2 blink while you keep them pressed. Hold them until the LEDs begin blinking at double the rate (approximately 10 seconds.) Release the buttons and the keypad will reset.

NOTE: When you reset a ControlPad or Keypad, the device is restored to the factory default, so you will lose any scripts, IRL files, Device Interrogation settings, or RMS server information loaded on the system.

- Restore the factory image on the ControlPad or Keypad: Press the ID pushbutton for approximately 20 seconds or longer
 during the boot process. While pressing the ID pushbutton, disconnect and reconnect the cable from the LAN port on the
 rear panel of the device to restore the factory image firmware on the ControlPad.
- Toggle between a DHCP or static IP address. See the *Toggling Between IP Addressing Modes: DHCP and Static IP* section on page 26 for more information.

In place of using the ID pushbutton, you can press buttons 1 and 2 simultaneously on the ControlPad or keypad to simulate the functions of the ID pushbutton. You must keep both buttons pressed for approximately 10 or 20 seconds as you would with the ID pushbutton to perform a factory reset or restore the factory firmware image on the device. You must also disconnect and reconnect the cable from the LAN port while pressing the buttons. FIG. 14 displays the locations of buttons 1 and 2 on each Massio device.





Rotate counter-clockwise = Button #13

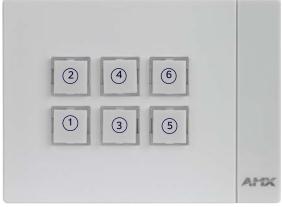
Rotate clockwise = Button #12

6-button (portrait)

FIG. 14 Button layout for Massio ControlPads and Keypads

NOTE: RPM applies a different numbering scheme in its background for the ControlPads. Disregard any button pushes you see in NetLinx Studio.

The button assignments are the same on the portrait and landscape versions of the MCP-106 and MKP-106. On a landscape installation, button 1 is in the lower left corner of the device (see FIG. 15).

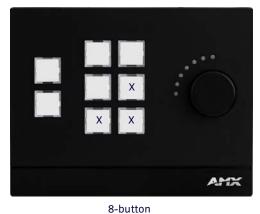


6-button (landscape)

FIG. 15 Button layout (6-button landscape)

You can also simultaneously press buttons 4, 5, and 6 to power cycle the device. Press all three buttons simultaneously and hold them for 20 seconds to power cycle the device (see FIG. 16).

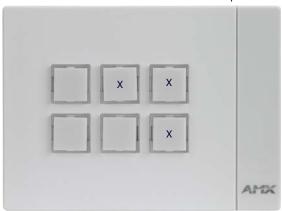




6-button (portrait)

FIG. 16 Press buttons marked with X to power cycle the device

On a landscape installation, consult FIG. 17 for the locations of the button to press for a power cycle.



6-button (landscape)

FIG. 17 Press buttons marked with X to power cycle the device

Installation

Overview

This chapter describes installing Massio ControlPads and Keypads. The MCP-106 and MKP-106 mount onto standard 1 gang US, UK, or EU back boxes. The MCP-108 and MKP-108 mount onto standard 2 gang US, UK, or EU back boxes.

NOTE: Before touching the device, discharge the static electricity from your body by touching a grounded metal object.

NOTE: It is best to install button labels before mounting the device. Doing so keeps you from disassembling the ControlPad after mounting it. For instructions on installing button labels, see the Button Labeling section on page 20.

Mounting Procedures

AMX recommends mounting each type of ControlPad or Keypad in standard a conduit box per NEC specs section 370. You can mount the MCP-108 and MKP-108 to a podium using the provided metal mounting bracket.

NOTE: Before installing and mounting the device, you should test it to see that it can receive power. See the Applying Power section on page 15 for more information.

Wallbox Mounting

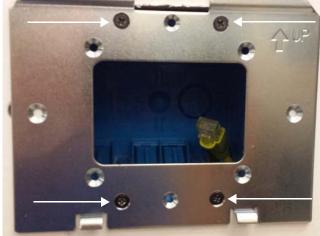
Perform these steps to mount the device into a back box:

 Install the back box into the surface of the desired location for the device. Be sure to thread any appropriate wiring through the back box.

IMPORTANT: Leave 3/8" (9.52mm) of space between the top of the mounting bracket and any overhanging or otherwise obstructing surface. The extra space is required for attaching the device frame to the mounting bracket.

2. Once the back box is installed and secured, secure the metal mounting bracket to the back box using the provided screws. FIG. 18 displays the location of the screw holes for the metal mounting brackets for each type of Massio device.





MCP-106

MCP-108

FIG. 18 Location of screw holes on metal mounting brackets.

- Peel the plastic covering off of the insulator on the rear panel of the device. You can discard the plastic covering after removing it.
- 4. Make all necessary connections to the ports on the rear panel of the ControlPad. Be sure to connect category cable to the LAN port to supply power to the device. See the *Applying Power* section on page 15 for more information.
- 5. Attach the device frame to the mounting bracket by hooking the top of the device frame onto the extended lip at the top of the mounting bracket.

FIG. 19 illustrates how to connect the device frame to the mounting bracket.

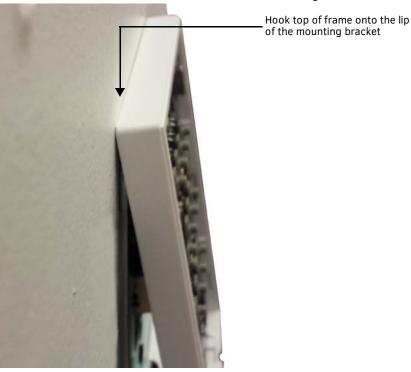
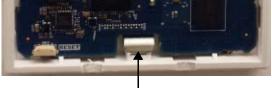


FIG. 19 Attaching the frame to the mounting bracket (MCP-106 displayed)

- 6. Press the sides of the device frame to snap them into place.
- 7. Press the bottom corners of the device frame to snap them into place. The metal clip on the mounting bracket should align with the open spaces located at the bottom of the device frame. The clip should fit inside this space and lock the device frame into position on the mounting bracket. There are two metal clips on the 8-button Massio devices. There is only one on the 6-button devices.

FIG. 20 displays the location of the metal clip on the 6-button devices.



Metal clip from mounting bracket

FIG. 20 Metal clip from mounting bracket locking device frame onto bracket FIG. 21 displays the locations of the metal clips on the 8-button devices.



Metal clips from mounting bracket

 $\textbf{FIG. 21} \hspace{0.2cm} \textbf{Metal clips from mounting bracket locking device frame onto bracket} \\$

8. Connect the faceplate to the device frame by snapping the top corners of the faceplate into place on the device frame. If connected properly, the faceplate should hold itself in place against the device frame.

NOTE: If you need to label the buttons on the device or replace any key caps, it is best to do so before attaching the faceplate. Consult the Button Labeling section on page 20 for instructions.

9. Press the bottom corners of the faceplate until each corner snaps into place with the device frame.

Button Labeling

Overview

Massio ControlPads and Keypads come with a set of clear plastic Button Caps which are designed to fit tightly over the pushbuttons, and allow you to place a label on each button according to the requirements of your particular installation.

Massio devices also come with a pre-printed acetate sheet with a range of 70 (pre-cut) button label inserts. The button labels provided will accommodate most installations, but it is also possible to print your own button labels on acetate for custom button labeling.

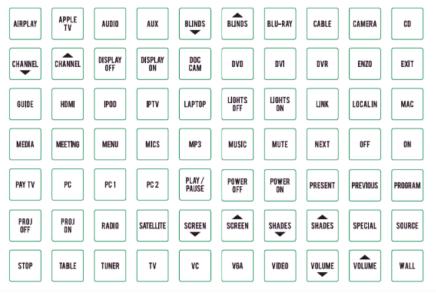


FIG. 22 Acetate sheet of 70 standard button labels (pre-cut)

Installing Acetate Button Labels

Follow these instructions to install the acetate button labels and Button Caps:

- 1. Remove the faceplate from the device.
- 2. Remove the cone and diffuser from the button. The cone and diffuser are adhered together and should not be separated.
- 3. Peel off the desired Button Label from the included acetate sheet. If you have printed your own custom button labels on acetate, cut each button label to fit inside the Button Caps.
 - Custom button labels must be cut to a 14mm (0.55") square to fit securely inside the Button Caps.
 - The thickness of the acetate used must not exceed .004" (0.10 mm).
- 4. Place the Button Cap face-down, and insert the Button Label into the bottom of the Button Cap (FIG. 23).
 - Orient the Button Label inside the Button Cap so that the two clips are located on the top and bottom sides of the readable text on the Button Label, as indicated in FIG. 23.
 - Be sure to place the Button Label face-down inside the Button Cap, otherwise the label will be seen in reverse.

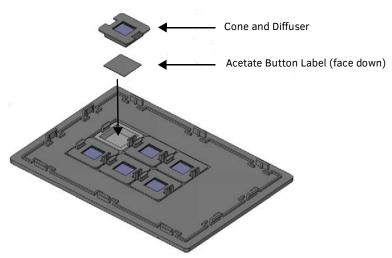


FIG. 23 Placing a Button Label inside a Button Cap

- 5. Place the cone and diffuser back over the button and snap the cone into place on the faceplate.
- 6. Repeat steps 2-5 for any additional buttons. When finished, mount the faceplate back onto the device.

Disassembling the Massio Device

If you are replacing button labels after you have already installed and mounted the Massio device, follow these steps to disassemble the device.

NOTE: Remove power from the Massio device, and discharge any static electricity from your body by touching a grounded metal object before performing the following steps.

This procedure requires a flat-head screwdriver.

1. Use the flat-head screwdriver to locate the two small ridges at the bottom of the faceplate and gently pry the faceplate away from the device frame. The two ridges are located toward the center of the faceplate on the 6-button Massio devices. They are located toward the sides of the device on the 8-button Massio devices (see FIG. 24).

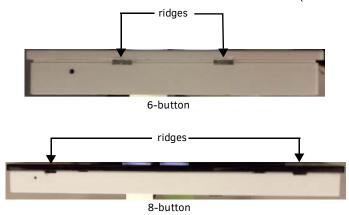


FIG. 24 Location of the ridges on the bottom of each Massio device

- 2. Lift the faceplate away from the rear panel to expose the device frame.
- Remove device frame from the mounting bracket by inserting the flat-head screwdriver below the metal clip located at the bottom center of the device frame and lifting the clip upward to unlock the device frame from the mounting bracket (see FIG. 25).

FIG. 25 illustrates using a flat-head screwdriver to unlock the device frame of an MCP-106 from the metal clip on the mounting bracket.

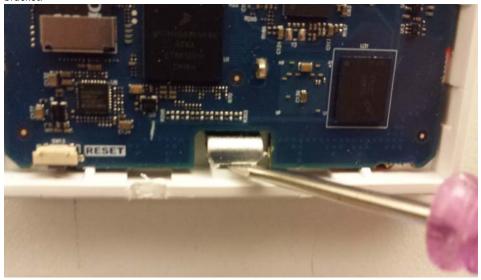


FIG. 25 Unlocking the device frame from the mounting bracket

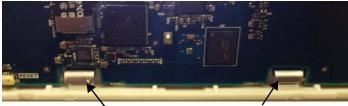
4. When the device frame is unlocked from the mounting bracket, lift the device frame upward and away from the top lip of the mounting bracket.

Re-Assembling the Massio Device

Follow these steps to re-assemble the Massio device.

- Make all necessary connections to the ports on the rear panel of the device. Be sure to connect category cable to the LAN port
 to supply power to the device. See the Applying Power section on page 15 for more information.
- 2. Attach the device frame to the mounting bracket by hooking the top of the device frame under the extended lip(s) at the top of the mounting bracket.
- 3. Press the sides of the device frame to snap them into place.
- 4. Press the bottom corners of the device frame to snap them into place. The metal clips on the mounting bracket should align with the open spaces located at the bottom of the device frame. The clips should fit inside these spaces and lock the device frame into position on the mounting bracket. There are two metal clips on the 8-button Massio devices. There is only one on the 6-button Massio devices.

FIG. 26 displays the locations of the metal clips on the 8-button Massio devices.



Metal clips from mounting bracket

FIG. 26 Metal clips from mounting bracket locking device frame onto bracket FIG. 27 displays the location of the metal clip on the 6-button Massio devices.



Metal clip from mounting bracket

FIG. 27 Metal clip from mounting bracket locking device frame onto bracket

- 5. Connect the faceplate to the device frame by pressing the top corners of the faceplate until they snap into place on the device frame. If connected properly, the faceplate should hold itself in place against the device frame.
- 6. Press the bottom corners of the faceplate until each corner snaps into place with the device frame.

Initial Configuration

Massio ControlPads

This section describes using the NetLinx Studio software application to perform the initial configuration of the Massio ControlPad. You can use NetLinx Studio to perform the following configuration options on a Massio ControlPad:

- Set up a System number
- · Obtain/assign the IP/URL for the ControlPad
- Transfer firmware Kit files to the ControlPad see the Upgrading Firmware section on page 28

You can perform other configuration and programming options on Massio ControlPads by using Rapid Project Maker (RPM) available at www.amx.com. Massio ControlPads do not directly accept NetLinx code. You can only send NetLinx commands to a Massio ControlPad through a Terminal (Telnet) window.

For information on configuring the Massio Keypad, see the Massio Keypads section on page 27.

NOTE: You can also configure the ControlPad using the NetLinx Diagnostics 3 application, which is a companion application for RPM for configuration and management of Massio ControlPads. It is a lightweight application that does not include the integrated development environment for NetLinx code. It may be a more suitable and recommended application, although in larger sites where both NX controllers and Massio ControlPads are being installed, NetLinx Studio is the preferable application.

Before You Start

- Verify you have the latest version of the NetLinx Studio application version 4.0 installed on your PC.
 NetLinx Studio is available to download from www.amx.com. Login to download the latest version. Alternatively, if it is already installed, use the Web Update option in NetLinx Studio's Help menu to obtain the latest version.
 The default location for the NetLinx Studio application is Start > Programs > AMX Control Disc > NetLinx Studio > NetLinx
- 2. Verify that a LAN cable is connected from the ControlPad to a PoE injector or a PoE-capable Ethernet switch, and the PoE switch is connected to the LAN Hub. If connected correctly, the ControlPad should receive power.

Obtaining the ControlPad's IP Address

Rapid Project Maker (RPM) requires the IP address of the ControlPad for configuration. Perform the following steps to retrieve the IP address of the ControlPad. To assign a static IP address to the ControlPad, see the *Changing the ControlPad's Network Address Information* section on page 24 for more information.

NOTE: Massio ControlPads use DHCP addressing by default.

NOTE: Verify there is an active LAN connection on the ControlPad's LAN port before beginning these procedures.

Open RPMLoader and click Communications Settings to open the Connect to Master dialog (FIG. 28).

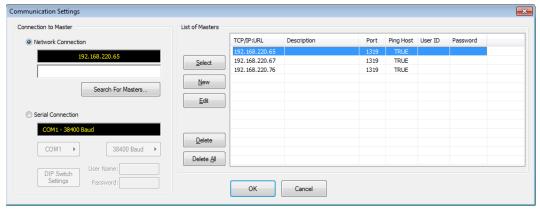


FIG. 28 Communications Settings dialog

2. Under Connection to Master, select **Network Connection**.

3. Click Search For Masters to search the network for online Masters in the Search for Masters dialog (FIG. 29).

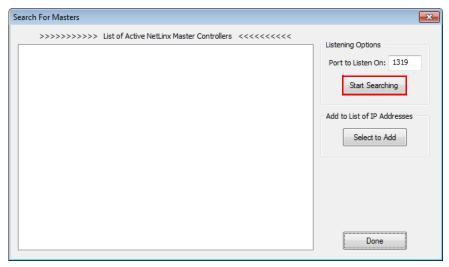


FIG. 29 Search for Masters dialog

- 4. Click Start Searching to begin listening for "blink" (UDP) messages from NetLinx Masters on the subnet.
- 5. When you see the IP Address for the ControlPad in the List of Active NetLinx Master Controllers, click **Stop Listening**. The IP address of the ControlPad is listed in the TCP/IP column of the dialog.

Changing the ControlPad's Network Address Information

1. Select Options > Master's Network Address to open the Master Controller's Network Address dialog (FIG. 30):

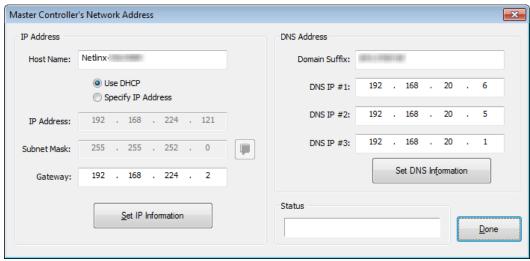


FIG. 30 Master Controller's Network Address dialog

- 2. Edit the **IP Address** fields as necessary:
 - Host Name: Use this field to view/edit the ControlPad's current Host Name.
 - Use DHCP/ Use these radio buttons to specify whether to use DHCP, or to Specify an IP Address for the Specify IP Address: ControlPad. DHCP is selected by default.

NOTE: If you select DHCP, the IP Address and Subnet Mask fields (below) are disabled for editing.

- IP Address: Use this field to view/edit the ControlPad's current IP Address.
- Subnet Mask: Use this field to view/edit the ControlPad's current Subnet Mask assignment. Click the help icon to open the Valid Subnet Masks help topic, which lists valid subnet masks, and the maximum

number of IP hosts allowed for each.

- Gateway: Use this field to view/edit the ControlPad's current Gateway assignment.
- \bullet Set IP Information: Sets the new IP information, as indicated in this dialog.

NOTE: RPMLoader will reboot the ControlPad when the Set IP Information button is clicked.

3. Click the **Set IP Information** button to set the new IP address information on the ControlPad. The program will prompt you that the Master Controller will be rebooted when this button is pressed (click **OK** to proceed).

- 4. Edit the DNS Address fields as necessary:
 - Domain Suffix: Use this field to view/edit the target master's current Domain Suffix.
 - DNS IP #1, #2, #3: Use these fields to view/edit the target master's current DNS IP address(es).
 - Set DNS Information: Sets new DNS IP information, as indicated in this dialog.

Note: The Master Controller does not require a reboot if only changing DNS information.

- Click the Set DNS Information button to set the new IP address information on the ControlPad. It is not necessary to reboot the ControlPad if only the DNS Address information is changed.
- 6. Click Done to close this dialog.

Connecting to the ControlPad via USB

If you do not have a DHCP server or if the ControlPad has an unknown static IP address, you can obtain the IP address of the controller via USB.

- 1. Using a standard Micro-USB cable, connect the Program Port on the rear panel of the ControlPad to your PC.
- 2. In NetLinx Studio, select **Settings > Workspace Communications Settings** to open the Workspace Communication Settings dialog.

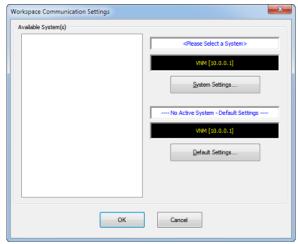


FIG. 31 Workspace Communication Settings dialog

3. Click System Settings to open the Communication Settings dialog.

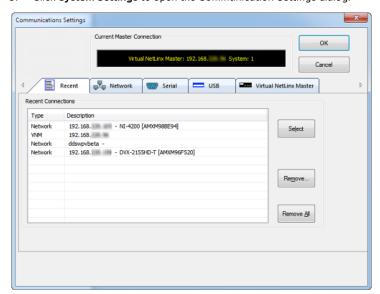


FIG. 32 Communication Settings dialog - Recent tab

4. Select the **USB** tab. The USB tab features a list of devices connected to your PC via USB. The IP address of the ControlPad appears in the IPv4 Address column.

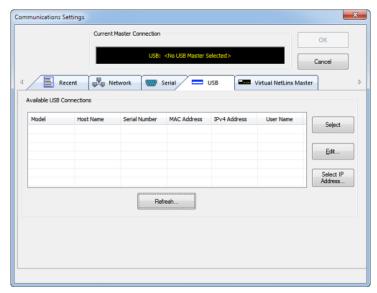


FIG. 33 Communications Settings dialog - USB tab

5. Highlight your ControlPad and click Select to connect to it.

Toggling Between IP Addressing Modes: DHCP and Static IP

Massio ControlPads support both DHCP and static IP addresses. You can use a static IP address which you can set via a Telnet command (SET IP), or you can use the factory default static IP address (192.168.1.3). The default static IP address can be recalled at any time by resetting the unit to its factory default configuration.

You can toggle between the DHCP and Static IP modes by pressing the ID Pushbutton located on the bottom of the ControlPad. After the ControlPad boots, press and hold the ID Pushbutton for 10 seconds. While pressing the ID pushbutton, disconnect and reconnect the cable from the LAN port on the rear panel of the ControlPad to toggle between IP addressing modes.

NOTE: You must wait until the ControlPad is finished booting before toggling the IP address. Pressing the pushbutton while booting will cause the ControlPad to restore its factory default settings.

When you release the Pushbutton, the switcher toggles either from static to dynamic (DHCP) IP addressing or vice versa and remains in that mode until the you use ID Pushbutton to toggle the IP mode again or you perform a factory reset. The switcher automatically reboots to complete the process.

In place of using the ID pushbutton, you can press buttons 1 and 2 simultaneously on the ControlPad to simulate the functions of the ID pushbutton. You must keep both buttons pressed for 10 seconds as you would with the ID pushbutton to toggle between IP address modes. See the *ID Pushbutton* section on page 16 for the button locations for each type of ControlPad.

Configuration and Programming

You can configure Massio ControlPads with RPM. RPM is a cloud-based configuration tool that allows you to easily configure an AMX system by using a step-by-step wizard-based approach. You can get started using RPM by accessing it via the AMX Services Home page at https://my.amx.com.

For more information on using RPM, see the RPM Instruction Manual available at www.amx.com.

Programming

Massio ControlPads do not directly accept NetLinx code. You can only send NetLinx commands to a Massio ControlPad through a Terminal (Telnet) window.

For more information about NetLinx Programming and Terminal (Telnet) commands, see the NX-Series WebConsole and Programming Guide available at www.amx.com.

WebConsole

Massio ControlPads have a built-in WebConsole that allows you to make various configuration settings via a web browser on any PC that has access to the ControlPad. These pages are available by accessing the ControlPad via NetLinx Studio or any compatible web browser.

Accessing the WebConsole

From any PC that has access to the LAN on which the target ControlPad resides:

- 1. Open a web browser and type the IP address of the target ControlPad in the Address Bar.
- 2. Press Enter to access WebConsole for that ControlPad. The initial view is the Web Control page.

Default User Names and Passwords

The following table lists the default user names and passwords for accessing the Massio ControlPads through NetLinx Studio or the WebConsole.

Default User Names and Passwords			
User Name Passwor			
NetLinx Studio	netlinx	password	
WebConsole administrator password			

For more information about navigating and the features of the WebConsole, see the NX-Series WebConsole and Programming Guide available at www.amx.com.

Massio Keypads

The following sections provide instructions on accessing and configuring the keypad.

Locating the IP Address of the Keypad

The MKP-106 is configured for DHCP addressing by default. The keypad uses link local addressing as a backup in case the DHCP server is inaccessible. See the *Toggling Between IP Addressing Modes: DHCP and Static IP* section for information on setting a static IP address. Verify there is an active LAN connection on the controller's LAN port before beginning this procedure.

- 1. Using category cable, connect the LAN port on the keypad to your external network.
- 2. In NetLinx Studio, select the OnLine Tree tab. You should see the Keypad listed among the Unbound Devices.
- Right-click the Keypad and select Network Bind/Unbind Device from the menu that appears. The Bind/Unbind Device dialog opens.
- 4. By default, the selected keypad appears in the Device to Bind/Unbind menu at the top of the dialog. If there is more than one Unbound device in the system, click the down arrow to select which device you want to bind.
- 5. Select the check box next to the Master to which you want to bind the keypad. If there is more than one Master in the system, check the specific Master to which you want to bind the keypad.
- 6. Click OK to save changes and close this dialog.
- 7. Select Refresh System (in the Online Tree context menu). The device should now appear in the Bound Devices folder.

Toggling Between IP Addressing Modes: DHCP and Static IP

Massio Keypads support both DHCP and static IP addresses. You can use a static IP address which you can set via a Telnet command (SET IP), or you can use the factory default static IP address (192.168.1.2).

With the keypad powered and booted up (or in ID Mode), you can toggle between the DHCP and Static IP modes by pressing and holding buttons 1 and 2. The LEDs on buttons 1 and 2 blink while you keep them pressed. Hold them until the LEDs begin blinking at double the rate (approximately10 seconds), then release the buttons.

When you release the buttons, the keypad toggles either from static to dynamic (DHCP) IP addressing or vice versa and remains in that mode until the you use the buttons to toggle the IP mode again or you perform a factory reset. The keypad automatically reboots to complete the process.

NOTE: You must wait until the keypad is finished booting before toggling the IP address. Pressing the buttons while booting will cause the keypad to restore its factory default settings.

Upgrading Firmware

Overview

The basic process of upgrading firmware on Massio ControlPads involves downloading the latest firmware files from www.amx.com and using NetLinx Studio to transfer the files to a target ControlPad.

Use the OnLine Device tree in NetLinx Studio to view the firmware files currently loaded on the device. FIG. 34 shows an example OnLine Tree indicating an MCP-108:

```
□ System 2 Devices [10.: ]
□ □ 00000 - MCP-108 Master (v1.3.23)
□ □ 05001 - MCP-108 (1.1.18)
```

FIG. 34 NetLinx Studio - Sample OnLine Tree

While the method of upgrading firmware files is the same for all Massio ControlPads, there are some specific points relative to the specific model and type of controller that must be noted:

Massio ControlPads - Firmware Files

Massio ControlPads contain two devices (*Master* and *Device Controller*), each of which require a separate firmware (*.kit) file. The ControlPad firmware file is not the same as the Device Controller firmware file. These two devices must be kept at compatible firmware versions for proper operation. Therefore, both files should be used when upgrading any firmware associated with the

Master Firmware	The on-board Master is listed first in the OnLine Tree as "00000 MCP-10x Master (<firmware version="">)"</firmware>	
	For example, the Master in FIG. 34 above is "00000 - MCP-108 Master (v1.3.23)".	
	 "00000" represents Device ID 0, which is reserved for the Master The number in parenthesis (in this case "v1.3.23") is the current Master firmware version 	
Device Controller Firmware	The Device Controller is listed next as "05001 MCP-10x (<firmware version="">)" For example, the Device Controller in FIG. 34 above is "05001 - MCP-108 (v1.1.18)". • "05001" represents Device ID 5001, which is reserved for the Device Control ports. • The number in parenthesis (in this case "v1.1.18") is the current Device Controller firmware version.</firmware>	

Before You Start

Integrated Controllers.

- 1. Verify you have the latest version of the NetLinx Studio application installed on your PC.
 - NetLinx Studio is available to download from www.amx.com. Login to download the latest version. Alternatively, if it is already installed, use the **Web Update** option in NetLinx Studio's Help menu to obtain the latest version.
 - The default location for the NetLinx Studio application is **Start** > **Programs** > **AMX Control Disc** > **NetLinx Studio** > **NetLinx Studio**.
- 2. Verify that a LAN cable is connected from the controller to the LAN Hub.
- 3. Verify that the controller is powered on.
- 4. Connect to the controller via IP address.
- 5. Establish what version of firmware is currently loaded on the controller (see Verifying the Current Firmware Version below).

Verifying the Current Firmware Version

Use the OnLine Tree in NetLinx Studio (see FIG. 34 on page 28) to verify which version of each firmware file is currently installed.

NOTE: These steps assume that you have already established a connection with the target ControlPad (see the Initial Configuration section on page 23 for details).

- 1. In NetLinx Studio, click on the OnLine Tree tab (in the Workspace Bar) to view the devices on the System.
- 2. Click **Display** and select **Refresh System** from the context menu. This establishes a new connection to the System and populates the device tree with devices on that system.
- 3. After the Communication Verification dialog indicates active communication between the PC and the Central Controller, verify the Central Controller and associated devices are listed in the OnLine Tree.
- Check the appropriate product page on www.amx.com for the latest Master and Device Controller firmware files for your device.

If necessary, follow the procedures outlined in the following sections to obtain these firmware (*.kit) files from www.amx.com and then transfer the new firmware files to the device.

Downloading the Latest Firmware Files from www.amx.com

NetLinx Controllers

Massio ControlPads require two firmware (*.kit) files: *Master* firmware and *Device* firmware. The Master firmware file is not the same as the Device firmware file.

Both files should be used when upgrading any firmware associated with the Integrated Controllers.

NOTE: The process of downloading and transferring firmware files is the same for all types of firmware. However, it is important that the firmware files are upgraded in specific following order for Massio ControlPads (see the Required Order of Firmware Updates section on page 29).

Master and Device Firmware Kit Files for Massio ControlPads

Below is a table outlining the Master and Device Firmware (*.kit) files used by Massio ControlPads:

Master and Device Firmware Files for Massio ControlPads		
MCP-106/108	Master Firmware: SW2102_MCP_10x_vx_x_xxx.kit	
	Device Firmware: SW2102_MCP_10x_Device_vx_xx_x.kit	
	HTTP Firmware Kit: SW2102_MCP_10x_vx_x_xxx-http.kit	

NOTE: The HTTP firmware kit enables you to upgrade firmware via an HTTP server. Follow the same steps in NetLinx Studio as you would with a typical firmware upgrade. Upgrading firmware via HTTP server is typically much faster than upgrading with the standard firmware kit files. See the Upgrading Firmware via NetLinx Studio section on page 30 for more information.

Downloading Massio ControlPad Firmware Files on www.amx.com

Visit the appropriate product page on www.amx.com for the latest *Master* and *Device Controller* firmware (*.kit) files for your Massio ControlPad. Firmware file links are available along the right-side of the catalog page.

Firmware files are bundled in a ZIP file, along with a Readme.TXT file that provides details on this firmware release.

- 1. Accept the AMX Licensing Agreement.
- 2. Download the ZIP file and unzip the contents to a known location.

Required Order of Firmware Updates

The *Upgrading Firmware via NetLinx Studio* instructions (below) apply equally to all types of firmware files. However, it is important that the firmware files are upgraded in the following order:

- 1. First, upgrade the **Device** firmware.
- 2. When that process is complete, upgrade the Master firmware.

Upgrading Firmware via NetLinx Studio

NOTE: These steps assume that you have already established a connection with the target ControlPad (IP connection is preferred.) See the Initial Configuration section on page 23 for details. You can also use the NetLinx Diagnostics application to upgrade firmware, if preferred.

- 1. In NetLinx Studio. click on the OnLine Tree tab (in the Workspace Bar) to view the devices on the System.
- 2. In the OnLine Tree tab, click **Display** and select **Refresh System** from the context menu. Doing so establishes a new connection to the System and populates the device tree with devices on that system.
- 3. After the Communication Verification dialog indicates active communication between the PC and the ControlPad, verify the Master and associated devices (including the Device Controller) are listed in the OnLine Tree.
- 4. In NetLinx Studio, select Tools > Firmware Transfers > Send to NetLinx Device (FIG. 35):



FIG. 35 NetLinx Studio - Tools > Firmware Transfers > Send to NetLinx Device

This option opens the Send to NetLinx Device dialog.

5. Click the *Browse* button (...) to locate and select the firmware (*.kit) file that will be transferred, in the *Browse for Folders* dialog (FIG. 36):

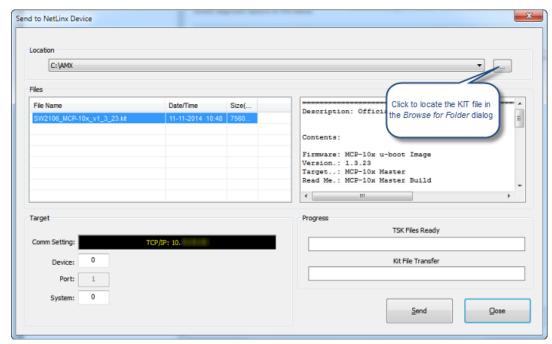


FIG. 36 NetLinx Studio - Send to NetLinx Device dialog

The selected file is indicated in the Files window.

- 6. Verify the target's System number matches the value listed within the active System folder in the OnLine Tree.
 - The Device number is always **0** for the ControlPad.
 - Note that the Port field is disabled (FIG. 37).

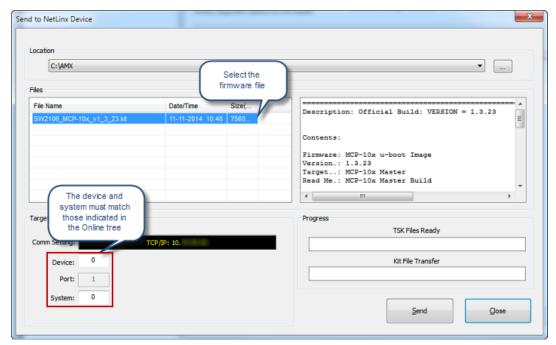


FIG. 37 Send to NetLinx Device dialog (showing on-board MCP-106 firmware update)

- 7. Click **Send** to begin the transfer. The file transfer progress is indicated in the *Progress* section of the dialog. The ControlPad reboots once the transfer is complete.
- 8. Click Close when the ControlPad is finished rebooting.
- In the OnLine Tree, right-click on the Master and select Refresh System. This establishes a new connection and refreshes the device list and their firmware versions in your system.

Once the process is complete, you can upgrade the remaining firmware files. All device files must be kept at compatible firmware versions for proper operation. Therefore, all files should be used when upgrading any firmware associated with the ControlPads. Be sure to follow the required order for installing firmware files. See the *Required Order of Firmware Updates* section on page 29 for more information.

Resetting the Factory Default System and Device Values

- 1. In NetLinx Studio, access the Device Addressing dialog:
 - Right-click on any system device listed in the Workspace and select Device Addressing.
 - Select **Diagnostics** > **Device Addressing** from the Main menu.
- 2. Click the Set Device/System to Factory Default button (FIG. 38):

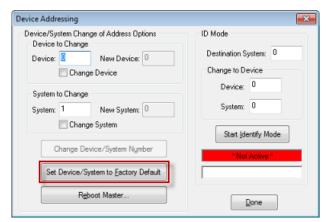


FIG. 38 Device Addressing dialog

This resets both the system value and device addresses (for definable devices) to their factory default settings. The system information (in the **OnLine Tree** tab of the Workspace window) refreshes and then displays the new information.

- 3. Click **Done** to close the *Device Addressing* dialog.
- 4. Click Reboot (from the Tools > Reboot the Master Controller dialog) and wait for the System Master to reboot.

NOTE: The STATUS and OUTPUT LEDs should begin to alternately blink during the incorporation. Wait until the STATUS LED is the only LED to blink.

- 5. Press **Done** once until the *Master Reboot Status* field reads *Reboot of System Complete*.
- 6. Click the OnLine Tree tab in the Workspace window to view the devices on the System.
- 7. Right-click the associated System number (or anywhere within the tab itself) and select **Refresh System**. This establishes a new connection to the specified System and populates the list with devices on that system.
- 8. Use **Ctrl+S** to save these changes to your NetLinx Project.

Programming

Programming the Massio Keypads

This chapter provides information on programming Massio Keypads, including NetLinx and Telnet commands.

Button Layouts

The following illustrations indicate the button numbers for each of the Massio Keypads (MKP-106 and MKP-108):



MKP-106 (Portrait)



Rotate counter-clockwise = Button #13
Rotate clockwise = Button #12
Push in = Button #11



MKP-106 (Landscape)

FIG. 39 Button Layout - Massio Keypads

Channels

Channels on Massio Keypads correspond to the button numbers on each keypad as indicated in FIG. 39.

Port Numbers and Levels

Massio Keypads support the following port numbers and levels:

Port Numbers and Levels			
Keypad Part	Port	Level	
Keypad Buttons	1	None	
Knob (MKP-108 only)	1	2, range is 0-255	
LED Bargraph (MKP-108 only)	1	1, levels indicate 0-255	

Programming the Knob and LED Bargraph (MKP-108)

The knob on the MKP-108 has multiple programming functions and can be treated from a NetLinx programming perspective as 1 pushbutton plus Channel up and down. The button layout for the knob is indicated in FIG. 39.

Knob - Button 11

The knob is a pushbutton that provide an event on Channel #11, and can be programmed like any other button.

Knob - Buttons 12-13

The knob itself can be rotated clockwise and counterclockwise, and is intended to provide level control (for example volume or lighting levels).

- When rotated clockwise, the knob provides events on Channel #12.
- When rotated counter-clockwise, the knob provides events on Channel #13.
- When rotated (clockwise/counter-clockwise), the knob provides level events on Level #2.

Navigation Wheel - Level Control

In addition to generating button events, a rotation of the knob causes a level change on Level #2:

- · Clockwise rotations increase the level
- Counter-clockwise rotations decrease the level.

Example code is provided below:

```
LEVEL_EVENT[dvMassio,2]
{
     volume = level.value
     SEND_STRING 0, "'Volume is now: ', ITOA(volume)"
}
```

Display Bargraph

The display bargraph consists of 7 LEDs and is controlled via Level #1. Sending a level will update the LEDs on the display bargraph. Example code is provided below:

```
SEND_LEVEL dvMassio,1,200
```

Supported SEND_LEVELs

MKP-108 keypads support a SEND_LEVEL on Level #1. This level is used to adjust the LED bargraph display on the keypad.

SEND_LEVELs	
SEND_LEVEL	Adjusts the LED bargraph display on the keypad.
	Syntax:
SEND_LEVEL <device address="">,1,<level></level></device>	
	Variables:
	level = LED bargraph display (range = 0 - 255).

Supported SEND_COMMANDs

Massio Keypads support a number of NetLinx SEND_COMMANDs, described in the following section. To use these commands, establish a Telnet session from the PC to the NetLinx master (see the *Establishing a Terminal Connection via Telnet* section on page 36 for more information.)

NOTE: All text is based on a Unicode index.

SEND_COMMANDS			
Command	Description		
@BRT	Set Brightness level for all LEDs (pushbuttons and levels indicator bar) for both On and Off states. Syntax:		
	Set Brightness level for all LEDs (pushbuttons and levels indicator bar) for both On and Off states. Syntax: #BBFT-con brightness (0-32)>, coff brightness (0-32)> Variables: on brightness = LED On brightness; ranges from 0 (off) to 32 (max). off brightness = LED Off level brightness; ranges from 0 (off) to 32 (max). Example: SEND_COMMAND keypad, 'eBRT-32,0' Sets the LEDs to max brightness in the On state (32), and minimum brightness (no illumination) in Off state (0). Sets the bargraph mode. NOTE: This command is only valid on the MKP-108 keypad. Syntax: 'BMODE-cbargraph mode 0-9>' Sets the specified bargraph to operate in one of the following modes: 0 = (default) normal bar mode 2 = special bar mode (a level of 1-32 still has first LED on) 8 = individual element, discrete mode 9 = inverse individual element, discrete mode Example: SEND_COMMAND keypad, 'BMODE-0' Allows NetLinx code to query the keypad to determine whether any expansion keypads are attached Syntax: 'EXPANSION EXEMPL_COMMAND DEVICE_1, "'?EXPANSION'" Response Syntax: "Expansion- <index>,<count>,<port>,<tp>,<description>" Count - total number of response strings (i.e. max # of expansion keypads allowed, currently 2) Port - Port associated with the expansion keypad Type - Expansion keypad type (either MET-7X or MET-13X) Description - Product description Example Response Strings when a single expansion keypad is present: "Expansion.Device-1, 2, 2, MET-7X, Metreau 7-Button Expansion Keypad* "Expansion.Device-2, 2, 3, NONE, NONE" Disable LEDs on the keypad. Syntax: LED-DIS Example: SEND_COMMAND DEVICE_1, "'LED-DIS'" Disable LEDs on DEVICE_1, "'LED-DIS'" Disable LEDs on the keypad. LEDs are enabled by default.</description></tp></port></count></index>		
	off brightness = LED Off level brightness; ranges from 0 (off) to 32 (max).		
	Example:		
	SEND_COMMAND keypad,'@BRT-32,0'		
	Sets the LEDs to max brightness in the On state (32), and minimum brightness (no illumination) in the Off state (0).		
BMODE	Sets the bargraph mode.		
	NOTE: This command is only valid on the MKP-108 keypad.		
	Syntax:		
	'BMODE- <bargraph 0-9="" mode="">'</bargraph>		
?EXPANSION			
	·		
	Index - response index, starting with 1		
	Count - total number of response strings (i.e. max # of expansion keypads allowed, currently 2)		
	Port - Port associated with the expansion keypad		
	Type - Expansion keypad type (either MET-7X or MET-13X)		
	Description - Product description		
	Example Response Strings when a single expansion keypad is present:		
	"Expansion.Device-1,2,2,MET-7X,Metreau 7-Button Expansion Keypad"		
	"Expansion.Device-2,2,3,NONE,NONE"		
LED-DIS	Disable LEDs on the keypad.		
	'		
	_		
LED-EN	Enable LEDs on the keypad. LEDs are enabled by default.		
	Syntax:		
	LED-EN		
	Example:		
	SEND_COMMAND DEVICE_1,"'LED-EN'"		
	Enables LEDs on DEVICE_1.		

SEND_COMMANDs (Cont.)	
Command	Description
REBOOT	Reboot the keypad.
	Syntax:
	REBOOT
	Example:
	SEND_COMMAND DEVICE_1,"'REBOOT'"
	Reboots DEVICE_1.
SET_NDX_DESC	Set Friendly name and location for NDP.
	Syntax:
	SET_NDX_DESC-friendly name:location
	Max of 25 characters for <i>friendly name</i> and max of 25 characters for <i>location</i> . If more than 25 characters are sent for either friendly name or location, they will be truncated to a max of 25 characters.
	Neither the friendly name nor the location should contain a ":" character, as that character is used as a delimiter.
	NOTE: This command requires a reboot to enable new settings.

Terminal (Telnet) Commands

Telnet terminal communication can be accessed remotely via TCP/IP.

Establishing a Terminal Connection via Telnet

- 1. In your Windows task bar, go to **Start > Run** to open the Run dialog.
- 2. Type cmd in the Open field and click OK to open an instance of the Windows command interpreter "Cmd.exe" (FIG. 40):

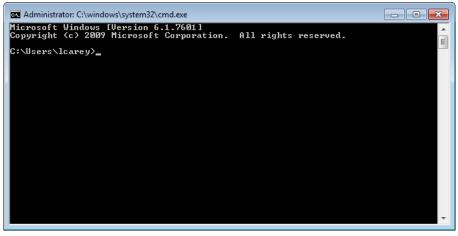


FIG. 40 Windows command interpreter (Cmd.exe)

3. Type "telnet" followed by a space and the keypad's IP address:

```
>telnet XXX.XXX.XXX
```

- 4. Press <Enter>.
 - Without a Telnet password set, a session will begin with a welcome banner similar to the following:

```
Welcome to MKP-108 v1.0.44 Copyright AMX LLC
```

• If a Telnet password is set, then user credentials are required:

```
Enter username:
Enter protected password:
Welcome to MKP-108 v1.0.44 Copyright AMX LLC >
```

Telnet User Name and Password

There are two Telnet commands that set the Telnet user name and password:

- Set Telnet Username (see page 41)
- Set Telnet Password (see page 41)

By default, both the user name and password are blank (empty string). Performing a factory reset on the device will return these values to that default. See the *ID Pushbutton* section on page 16 for details.

- Setting the *User Name* will have no effect if the password remains blank (empty string). That is, defining the user name alone will not result in Telnet prompting for user login.
- Setting the Password will cause Telnet to prompt for user login, whether the user name has been defined or not. If the user name has been defined, this value must be entered.

However, since the password can be set independently of the user name, it's possible to have a password defined, but the user name still at its default (blank, empty string).

In this case, do not enter anything for the user name when prompted. Simply press <Enter>, which will then present the password prompt. Here, the defined password must be entered, in order to successfully open the Telnet session.

Additional Notes

- Both the Telnet user name and password are case-sensitive.
- Three consecutive, unsuccessful attempts to log in to Telnet will cause the Telnet window to close. Re-launching Telnet will again present the login prompt, with a fresh "batch" of login attempts.
- If Telnet login fails because of an incorrect user name, you will receive the "Invalid Password" message (as opposed to an "Invalid Username" message).

Setting a Telnet User Name and Password

To set a Telnet user name and password:

- 1. Establish a terminal connection via Telnet.
- 2. Type Set Telnet Username, and press <Enter>. The program will prompt you to enter a new Telnet user name.
- 3. Enter a user name and press <Enter>. The program will indicate that the user name is being stored.
- 4. Type **Set Telnet Password**, and press <Enter>.

NOTE: Press < Enter> twice when asked to enter the password to clear both the telnet user name and password.

- 5. The program will prompt you to enter a password. Enter a password and press <Enter>.
- 6. The program will prompt you to re-enter the Telnet password. Re-enter the password and press <Enter>. The program will indicate that the password is being stored.

Telnet Commands

The commands listed in the following table can be sent directly to the Keypad via a Telnet terminal session.

In your terminal program, type "Help" or a question mark ("?") and <Enter> to access the Help Menu, and display the Program port commands described below:

Terminal Commands				
Command	Description			
? or Help	Display this list of commands.			
DEVICE STATUS	Display device status of a specified device, port, system (<d:p:s>). Example:</d:p:s>			
	>			
EXIT	Exit the telnet session			
FACTORYFWIMAGE	Reset unit to factory firmware image and reboots the Module.			
GET CONFIG	Display the current connection settings. Example: >get config Device number: 10001 Connection Settings ICSNet/Ethernet: Ethernet Mode: URL System Number: 1 Master IP/URL: 192.168.1.211 Master Port: 1319 Username: Password: IP Settings HostName: localhost Type: DHCP IP Address: 192.168.1.53 Subnet Mask: 255.255.255.0 Gateway IP: 192.168.1.1 MAC Address: 00:60:9f:94:2d:4f DNS Servers			
	NOTE: The system number and IP addressing information displayed is reflective of actual operating values, not stored parameters.			
GET CONNECTION	Show the Module connection information.			
GET CONNECTION	Example: >get connection Connection Settings ICSNet/Ethernet: Ethernet Mode: URL/TCP System Number: 1 Master IP/URL: 192.168.1.211 Master Port: 1319 Username: Password:			
GET DEVICE	Display the device number.			
GLI DEVICE	Display the device maniper.			

Terminal Commands (Co				
Command	Description			
GET DNS	Get list of DNS entries.			
	Example:			
	>get dns			
	DNS Servers			
	Domain suffix: amx.internal			
	Entry 1: 192.168.20.7			
	Entry 2: 192.168.20.9			
	NOTE: When the module is in DHCP mode, these are active values, NOT the stored values that only apply to static mode.			
GET ETHERNET MODE	Display the current LAN configuration setting.			
	Settings are either "auto" in which the LAN driver will discover it's settings based on the network			
	is connected to OR <speed> and <duplex> where speed is either 10 or 100 and duplex is either ful or half.</duplex></speed>			
	Example:			
	>GET ETHERNET MODE			
	Ethernet mode is auto.			
	NOTE: See the SET ETHERNET MODE command on page 40.			
GET FRIENDLY <name></name>	Displays the Module's friendly name (for NDP).			
GET IP	Displays the IP configuration of a device.			
	The device displays it's D:P:S, host name, type (DHCP or Static), IP address, subnet mask, gateway			
	IP, and MAC address.			
	Example:			
	>GET IP HostName MLK-INSTRUCTOR			
	Type DHCP			
	IP Address 192.168.21.101			
	Subnet Mask 255.255.255.0			
	Gateway IP 192.168.21.2 MAC Address 00:60:9f:90:0d:39			
GET LOCATION	Displays the location parameter for NDP (set by the SET LOCATION command on page 41)			
GET LOCATION GET SN	Displays the location parameter for NDP (set by the SET LOCATION command on page 41). Returns the device's serial number.			
GET SN	Returns the device's serial number			
GET SN INFO				
GET SN	Returns the device's serial number Provides at-a-glance information about the keypad including any expansion keypads that are attached to it. Enables/Disables extended diagnostic messages.			
GET SN INFO	Returns the device's serial number Provides at-a-glance information about the keypad including any expansion keypads that are attached to it. Enables/Disables extended diagnostic messages. • MSG On [error warning info debug] sets the terminal program to display log messages			
GET SN INFO	Returns the device's serial number Provides at-a-glance information about the keypad including any expansion keypads that are attached to it. Enables/Disables extended diagnostic messages. • MSG On [error warning info debug] sets the terminal program to display log messages generated by the Master.			
GET SN INFO	Returns the device's serial number Provides at-a-glance information about the keypad including any expansion keypads that are attached to it. Enables/Disables extended diagnostic messages. • MSG On [error warning info debug] sets the terminal program to display log messages generated by the Master. The level of log printed to the terminal window depends both on the level used when sending the message and the output level selected with "msg on."			
GET SN INFO	Returns the device's serial number Provides at-a-glance information about the keypad including any expansion keypads that are attached to it. Enables/Disables extended diagnostic messages. • MSG On [error warning info debug] sets the terminal program to display log messages generated by the Master. The level of log printed to the terminal window depends both on the level used when sending the message and the output level selected with "msg on." For example if log output is enabled via "msg on warning" then logs produced at levels AMX_ERROR and AMX_WARNING will be displayed, but not logs produced at levels AMX_INFO or			
GET SN INFO	Returns the device's serial number Provides at-a-glance information about the keypad including any expansion keypads that are attached to it. Enables/Disables extended diagnostic messages. • MSG On [error warning info debug] sets the terminal program to display log messages generated by the Master. The level of log printed to the terminal window depends both on the level used when sending the message and the output level selected with "msg on." For example if log output is enabled via "msg on warning" then logs produced at levels AMX_ERROR and AMX_WARNING will be displayed, but not logs produced at levels AMX_INFO or AMX_DEBUG.			
GET SN INFO	Returns the device's serial number Provides at-a-glance information about the keypad including any expansion keypads that are attached to it. Enables/Disables extended diagnostic messages. • MSG On [error warning info debug] sets the terminal program to display log messages generated by the Master. The level of log printed to the terminal window depends both on the level used when sending the message and the output level selected with "msg on." For example if log output is enabled via "msg on warning" then logs produced at levels AMX_ERROR and AMX_WARNING will be displayed, but not logs produced at levels AMX_INFO or AMX_DEBUG. The order of severity from highest to lowest is ERROR, WARNING, INFO, DEBUG.			
GET SN INFO	Returns the device's serial number Provides at-a-glance information about the keypad including any expansion keypads that are attached to it. Enables/Disables extended diagnostic messages. • MSG On [error warning info debug] sets the terminal program to display log messages generated by the Master. The level of log printed to the terminal window depends both on the level used when sending the message and the output level selected with "msg on." For example if log output is enabled via "msg on warning" then logs produced at levels AMX_ERROR and AMX_WARNING will be displayed, but not logs produced at levels AMX_DEBUG. The order of severity from highest to lowest is ERROR, WARNING, INFO, DEBUG. If no severity is supplied with "msg on", the default setting is WARNING.			
GET SN INFO	Returns the device's serial number Provides at-a-glance information about the keypad including any expansion keypads that are attached to it. Enables/Disables extended diagnostic messages. • MSG On [error warning info debug] sets the terminal program to display log messages generated by the Master. The level of log printed to the terminal window depends both on the level used when sending the message and the output level selected with "msg on." For example if log output is enabled via "msg on warning" then logs produced at levels AMX_ERROR and AMX_WARNING will be displayed, but not logs produced at levels AMX_INFO or AMX_DEBUG. The order of severity from highest to lowest is ERROR, WARNING, INFO, DEBUG. If no severity is supplied with "msg on", the default setting is WARNING. • MSG OFF disables the display.			
GET SN INFO	Returns the device's serial number Provides at-a-glance information about the keypad including any expansion keypads that are attached to it. Enables/Disables extended diagnostic messages. • MSG On [error warning info debug] sets the terminal program to display log messages generated by the Master. The level of log printed to the terminal window depends both on the level used when sending the message and the output level selected with "msg on." For example if log output is enabled via "msg on warning" then logs produced at levels AMX_ERROR and AMX_WARNING will be displayed, but not logs produced at levels AMX_DEBUG. The order of severity from highest to lowest is ERROR, WARNING, INFO, DEBUG. If no severity is supplied with "msg on", the default setting is WARNING.			
GET SN INFO	Returns the device's serial number Provides at-a-glance information about the keypad including any expansion keypads that are attached to it. Enables/Disables extended diagnostic messages. • MSG On [error warning info debug] sets the terminal program to display log messages generated by the Master. The level of log printed to the terminal window depends both on the level used when sending the message and the output level selected with "msg on." For example if log output is enabled via "msg on warning" then logs produced at levels AMX_ERROR and AMX_WARNING will be displayed, but not logs produced at levels AMX_INFO or AMX_DEBUG. The order of severity from highest to lowest is ERROR, WARNING, INFO, DEBUG. If no severity is supplied with "msg on", the default setting is WARNING. • MSG OFF disables the display. Example:			
GET SN INFO	Returns the device's serial number Provides at-a-glance information about the keypad including any expansion keypads that are attached to it. Enables/Disables extended diagnostic messages. • MSG On [error warning info debug] sets the terminal program to display log messages generated by the Master. The level of log printed to the terminal window depends both on the level used when sending the message and the output level selected with "msg on." For example if log output is enabled via "msg on warning" then logs produced at levels AMX_ERROR and AMX_WARNING will be displayed, but not logs produced at levels AMX_INFO or AMX_DEBUG. The order of severity from highest to lowest is ERROR, WARNING, INFO, DEBUG. If no severity is supplied with "msg on", the default setting is WARNING. • MSG OFF disables the display. Example: > MSG ON Extended diagnostic information messages turned on. > MSG OFF			
GET SN INFO MSG [ON OFF]	Returns the device's serial number Provides at-a-glance information about the keypad including any expansion keypads that are attached to it. Enables/Disables extended diagnostic messages. • MSG On [error warning info debug] sets the terminal program to display log messages generated by the Master. The level of log printed to the terminal window depends both on the level used when sending the message and the output level selected with "msg on." For example if log output is enabled via "msg on warning" then logs produced at levels AMX_ERROR and AMX_WARNING will be displayed, but not logs produced at levels AMX_INFO or AMX_DEBUG. The order of severity from highest to lowest is ERROR, WARNING, INFO, DEBUG. If no severity is supplied with "msg on", the default setting is WARNING. • MSG OFF disables the display. Example: > MSG ON Extended diagnostic information messages turned on. > MSG OFF Extended diagnostic information messages turned off.			
GET SN INFO MSG [ON OFF] NDP UNBIND	Returns the device's serial number Provides at-a-glance information about the keypad including any expansion keypads that are attached to it. Enables/Disables extended diagnostic messages. • MSG On [error warning info debug] sets the terminal program to display log messages generated by the Master. The level of log printed to the terminal window depends both on the level used when sending the message and the output level selected with "msg on." For example if log output is enabled via "msg on warning" then logs produced at levels AMX_ERROR and AMX_WARNING will be displayed, but not logs produced at levels AMX_INFO or AMX_DEBUG. The order of severity from highest to lowest is ERROR, WARNING, INFO, DEBUG. If no severity is supplied with "msg on", the default setting is WARNING. • MSG OFF disables the display. Example: > MSG ON Extended diagnostic information messages turned on. > MSG OFF Extended diagnostic information messages turned off. Clears the NDP binding to a master (takes effect after next boot).			
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GET SN INFO MSG [ON OFF] NDP UNBIND PING [ADDRESS]	Returns the device's serial number Provides at-a-glance information about the keypad including any expansion keypads that are attached to it. Enables/Disables extended diagnostic messages. • MSG On [error warning info debug] sets the terminal program to display log messages generated by the Master. The level of log printed to the terminal window depends both on the level used when sending the message and the output level selected with "msg on." For example if log output is enabled via "msg on warning" then logs produced at levels AMX_ERROR and AMX_WARNING will be displayed, but not logs produced at levels AMX_DEBUG. The order of severity from highest to lowest is ERROR, WARNING, INFO, DEBUG. If no severity is supplied with "msg on", the default setting is WARNING. • MSG OFF disables the display. Example: > MSG ON Extended diagnostic information messages turned on. > MSG OFF Extended diagnostic information messages turned off. Clears the NDP binding to a master (takes effect after next boot). Pings an address (IP or URL), to test network connectivity to and confirms the presence of another networked device. The syntax matches the PING application in Windows or Linux. Example: > ping 192.168.29.209 is alive.			
MSG [ON OFF] MSG [ON OFF] NDP UNBIND PING [ADDRESS]	Returns the device's serial number Provides at-a-glance information about the keypad including any expansion keypads that are attached to it. Enables/Disables extended diagnostic messages. • MSG On [error warning info debug] sets the terminal program to display log messages generated by the Master. The level of log printed to the terminal window depends both on the level used when sending the message and the output level selected with "msg on." For example if log output is enabled via "msg on warning" then logs produced at levels AMX_ERROR and AMX_WARNING will be displayed, but not logs produced at levels AMX_DEBUG. The order of severity from highest to lowest is ERROR, WARNING, INFO, DEBUG. If no severity is supplied with "msg on", the default setting is WARNING. • MSG OFF disables the display. Example: > MSG OFF Extended diagnostic information messages turned on. > MSG OFF Extended diagnostic information messages turned off. Clears the NDP binding to a master (takes effect after next boot). Pings an address (IP or URL), to test network connectivity to and confirms the presence of another networked device. The syntax matches the PING application in Windows or Linux. Example: > Ping 192.168.29.209 192.168.29.209 is alive. Reboots the keypad.			

Terminal Commands (Co	ont.)		
Command	Description		
RENEW DHCP	Renews/Releases the current DHCP lease for the keypad. Example: >RENEW DHCP		
RESET FACTORY	Resets the device's stored parameters to factory default state including removal of all security settings, resetting to DHCP. This command will cause an automatic reboot. NOTE: This command does not reset the device to the factory software image.		
SET CONNECTION	Set the master connection settings interactively, allowing the user to specify the mode. • If mode is TCP or UDP, the master URL and port number can be specified as well. • If AUTO is selected, the System number can be specified. • After all data is entered, if the parameters have changed, the Module will disconnect from the Master, and begin trying to connect with the new settings. NOTE: These changes do not require a reboot to take effect.		
SET DEVICE	Set the device number, and store in non-volatile memory. Syntax: SET DEVICE <num> The valid range of device numbers is 0-31999. If the user enters a number outside that range, then no change will be made and the Module will issue an error message. A Device Number of '0' means that the Module will accept the auto-assigned device number from the Master. If the new device number is different from the old device number, the Module will disconnect from the Master, and begin trying to connect with the new settings. NOTE: These changes do not require a reboot to take effect.</num>		
SET DNS	Set the DNS configuration of the EXB Module, only as applied to Static IP addressing mode (DNS settings in DHCP mode are received from the DHCP server). Syntax: SET DNS <d:p:s> This command prompts you to enter a Domain Name, DNS IP #1, DNS IP #2, and DNS IP #3. • Enter Y (yes) to approve/store the information in the Master. • Enter N (no) cancels the operation.</d:p:s>		
	NOTE: The device must be rebooted to enable new settings. Example: >SET DNS [0:1:0] Enter New Values or just hit Enter to keep current settings Enter Domain Suffix: amx.com Enter DNS Entry 1 : 192.168.20.5 Enter DNS Entry 2 : 12.18.110.8 Enter DNS Entry 3 : 12.18.110.7 You have entered: Domain Name: amx.com DNS Entry 1: 192.168.20.5 DNS Entry 2: 12.18.110.8 DNS Entry 3: 12.18.110.7 Is this correct? Type Y or N and Enter -> Y Settings written. Device must be rebooted to enable new settings		
SET ETHERNET MODE	This command sets the current LAN configuration settings per new mode. Syntax: SET ETHERNET MODE <newmode> Values for newmode are: auto - or - 10 100 full half NOTE: This command requires a reboot to enable new settings. Examples: set ethernet mode auto set ethernet mode 100 full NOTE: See the GET ETHERNET MODE command on page 39.</newmode>		

Terminal Commands (Co			
Command	Description		
SET FRIENDLY	Set the device's friendly name for NDP to <name>.</name>		
	Syntax:		
	 SET FRIENDLY <name></name> Maximum length = 25 characters. If the name entered exceeds 25 characters, it will be truncated 		
	The value is stored in non-volatile memory.		
	If no value specified, an automatic name consisting of AMX, the product name, and serial number		
	will be used.		
	NOTE: This command requires a reboot to enable new settings.		
SET IP	Sets the IP configuration of a specified device. Enter a host name, type (<i>DHCP</i> or <i>Fixed</i>), IP address, subnet mask, and gateway IP address.		
	NOTE: "DHCP" implies "DHCP with link-local fallback".		
	NOTE: For NetLinx Masters, the "Host Name" can only consist of alphanumeric characters.		
	Enter Y (yes) to approve/store the information into the Master.		
	Enter N (no) to cancel the operation.		
	NOTE: This command requires a reboot to enable new settings.		
	Example:		
	>SET IP		
	Enter New Values or just hit Enter to keep current settings		
	Enter Host Name: MLK_INSTRUCTOR		
	Enter IP type. Type D for DHCP or S for Static IP and		
	then Enter: DHCP Enter Gateway IP: 192.168.21.2		
	You have entered: Host Name MLK_INSTRUCTOR		
	Type DHCP Gateway IP 192.168.21.2		
	Is this correct? Type Y or N and Enter -> y		
	Settings written. Device must be rebooted to enable new settings.		
	NOTE: Metreau keypads can also be set to Static IP or DHCP Mode by using the ID Pushbutton.		
	See the Toggling Between IP Addressing Modes: DHCP and Static IP section on page 26 for details.		
SET LOCATION	Sets the location parameter for NDP.		
	Syntax:		
	 SET LOCATION <location></location> Maximum length = 25 characters. If the name entered exceeds 25 characters, it will be truncated 		
	NOTE: This command requires a reboot to enable new settings.		
SET TELNET PORT	Sets the device's IP port listened to for Telnet connections.		
	Example:		
	>SET TELNET PORT Current telnet port number = 23		
	Enter new telnet port number (Usually 23)(0=disable Telnet):		
	Once you enter a value and press <enter>, you get the following message:</enter>		
	Setting telnet port number to 23 New telnet port number set, reboot the device for the change to take effect.		
	NOTE: This command requires a reboot to enable new settings.		
	See the Enabling/Disabling Telnet on the Keypad section on page 42 for additional information.		
SET TELNET USERNAME	Set the user name for a secure Telnet session.		
	Default = blank (no user name required) See the Settion of Talact Version and Recovered eaction on page 37 for datails.		
OPT TELLIPE DAGGERS	See the Setting a Telnet User Name and Password section on page 37 for details. Set the Research for a secure Telesta section.		
SET TELNET PASSWORD	Set the Password for a secure Telnet session.		
	Default = blank (no password required) See the Setting a Talast Very Name and Password section on page 37 for details.		
	See the Setting a Telnet User Name and Password section on page 37 for details.		
SHOW CONNECTION LOG	Show the master connection log for the device.		

Terminal Commands (Cont.)					
Command	Description				
SHOW CONNECTION STATS	Show the connection statistics for the device. Output similar to the following example:				
	>show connection	stats			
	Connection Stati	stics			
		Total	Last 15 Minutes		
		=====	===========		
	ICSP Messages:	10039 received			
			d 333 transmitted		
	Blink Messages:	5014 received	166 received		
	IP Statistics:				
	RX packets:29298 errors:0 discarded:0				
	TX packets:15286 errors:0 discarded:0				
SHOW LOG	Display the message log.				
	Syntax:				
	SHOW LOG <start> • Use <start> to specify the message number to start displaying</start></start>				
	Use <all> to display</all>	Use <all> to display all messages.</all>			

Notes on Specific Telnet Clients

Telnet and terminal clients will have different behaviors in some situations. This section states some of the known anomalies.

Windows Client Programs

Anomalies occur when using a Windows™ client if you are not typing standard ASCII characters (i.e. using the keypad and the ALT key to enter decimal codes). Most programs will allow you to enter specific decimal codes by holding ALT and using keypad numbers.

For example, hold ALT, hit the keypad 1, then hit keypad 0, then release ALT. The standard line feed code is entered (decimal 10). Windows will perform an ANSI to OEM conversion on some codes entered this way because of the way Windows handles languages and code pages.

The following codes are known to be altered, but others may be affected depending on the computer's setup.

Characters 15, 21, 22, and any characters above 127.

This affects both Windows Telnet and Terminal programs.

Linux Telnet Client

The Linux Telnet client has three anomalies that are known at this time:

- A null (\00) character is sent after a carriage return.
- If an ALT 255 is entered, two 255 characters are sent (per the Telnet RAFT).
- If the code to go back to command mode is entered (ALT 29 which is ^]), the character is not sent, but Telnet command mode is entered.

Enabling/Disabling Telnet on the Keypad

By default, Telnet is enabled on all Metreau keypads. The default Telnet port is 23.

You can change the Telnet port by using the SET TELNET PORT command (see page 41). Setting the Telnet port to zero disables Telnet access.

The SET TELNET PORT command requires a reboot to enable new settings.

NOTE: Note: The only way to re-enable Telnet once it has been disabled is to reset the unit to the factory default firmware image. See the ID Pushbutton section on page 16 for details.





AMX does not assume responsibility for errors or omissions. AMX also reserves the right to alter specifications without prior notice at any time.

 $\label{thm:composition} The \ AMX \ Warranty \ and \ Return \ Policy \ and \ related \ documents \ can \ be \ viewed/downloaded \ at \ www.amx.com.$

